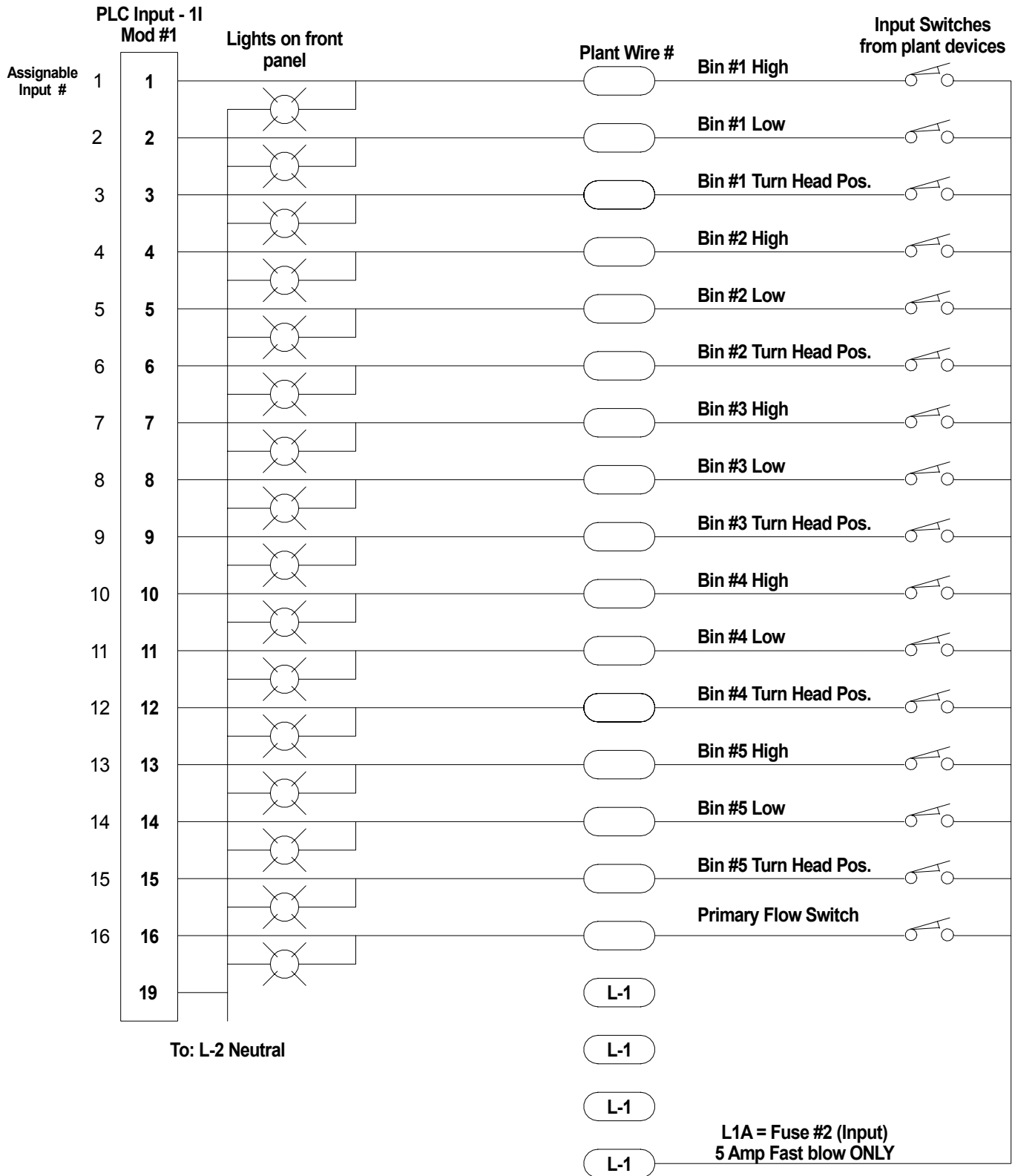


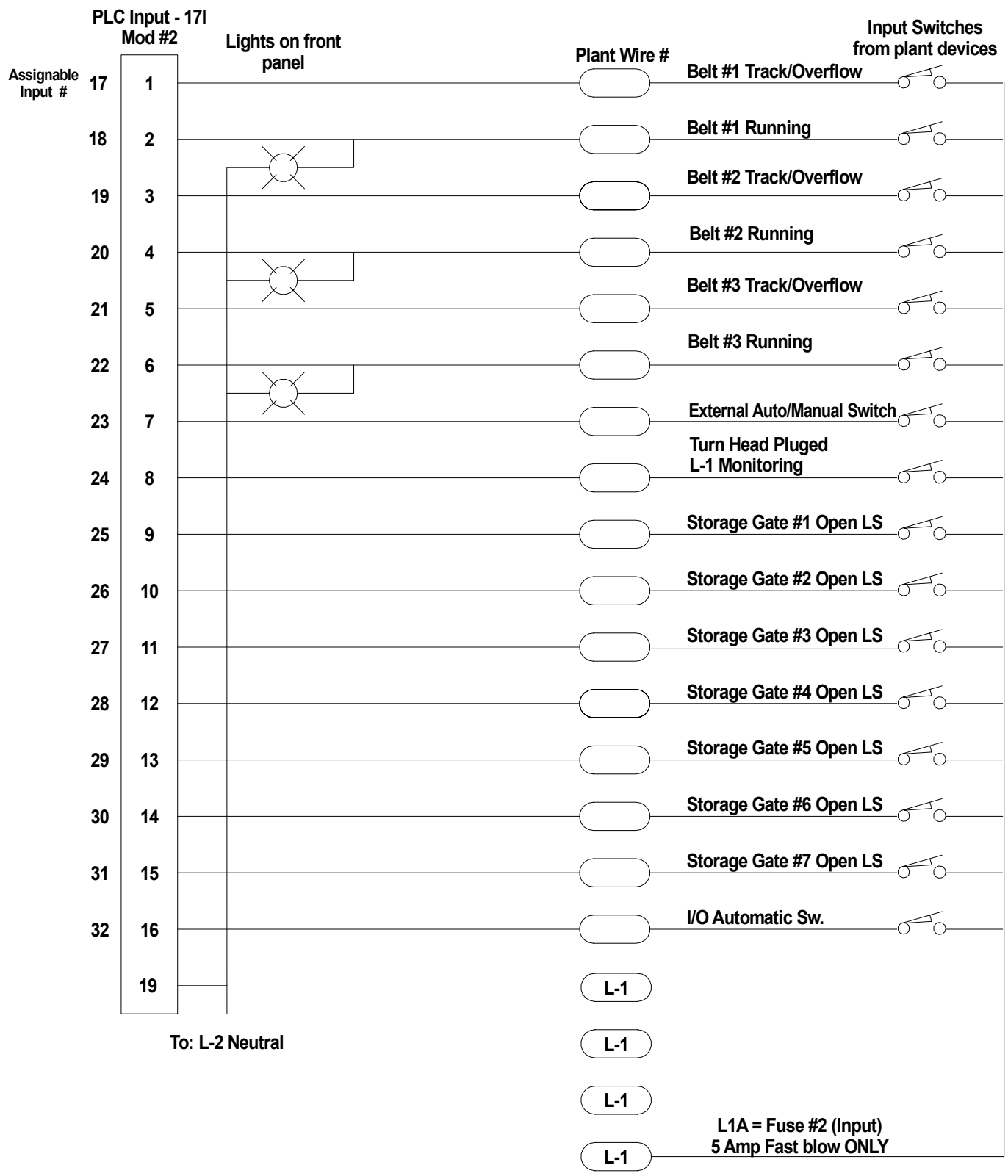
J.H.M.C. Robotics, Inc
 Plant wiring Diagrams.
 Cable Pull Logic Date: 04/16/2006

This Logic is on Input Page #2

NOTE: All Belt Pull cable switches are to BREAK contact when pulled.

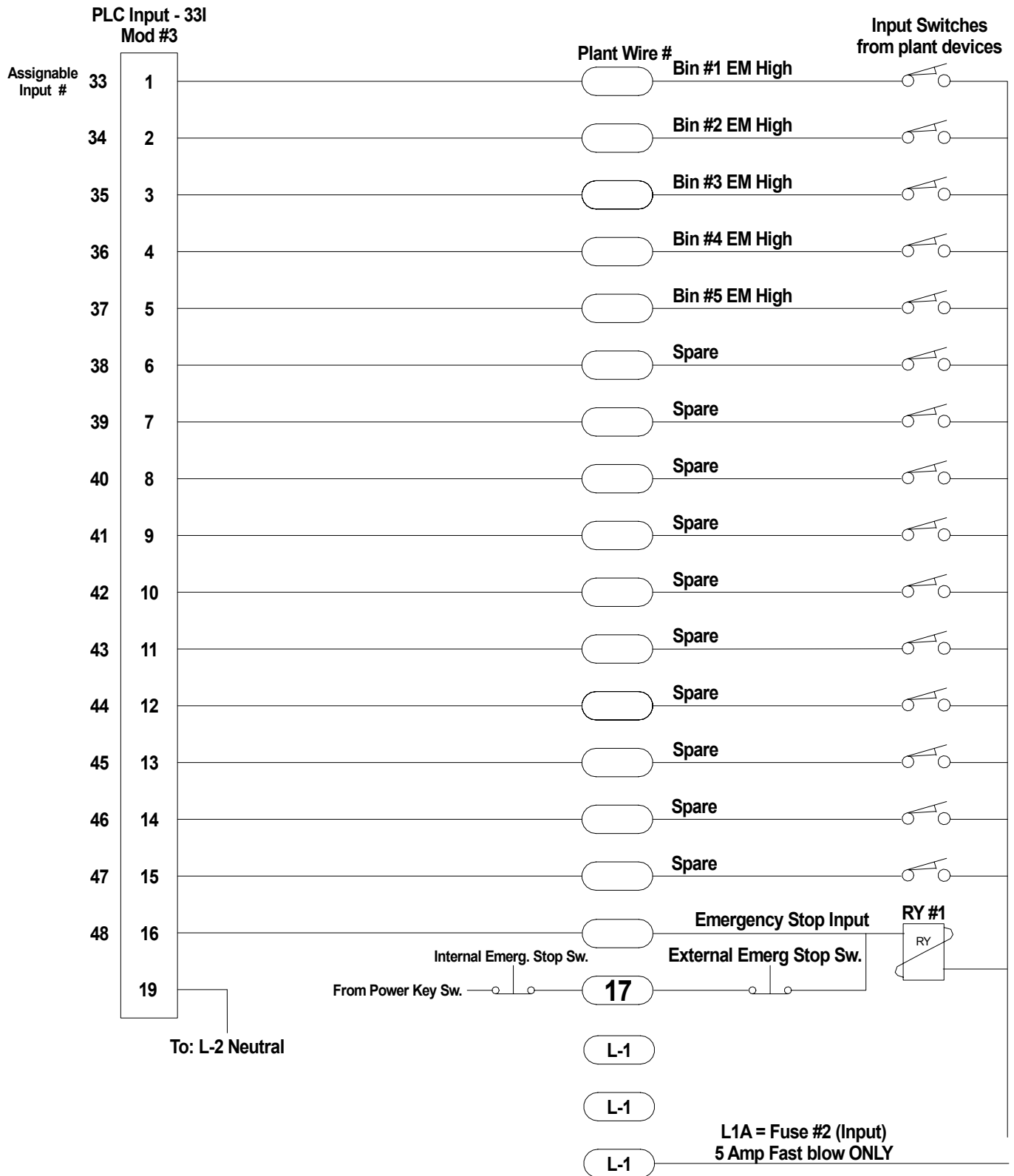


This 120 VAC can be used for powering Bindicators motors and other input related items.
Max. power = 5 Amps total ALL connected loads.

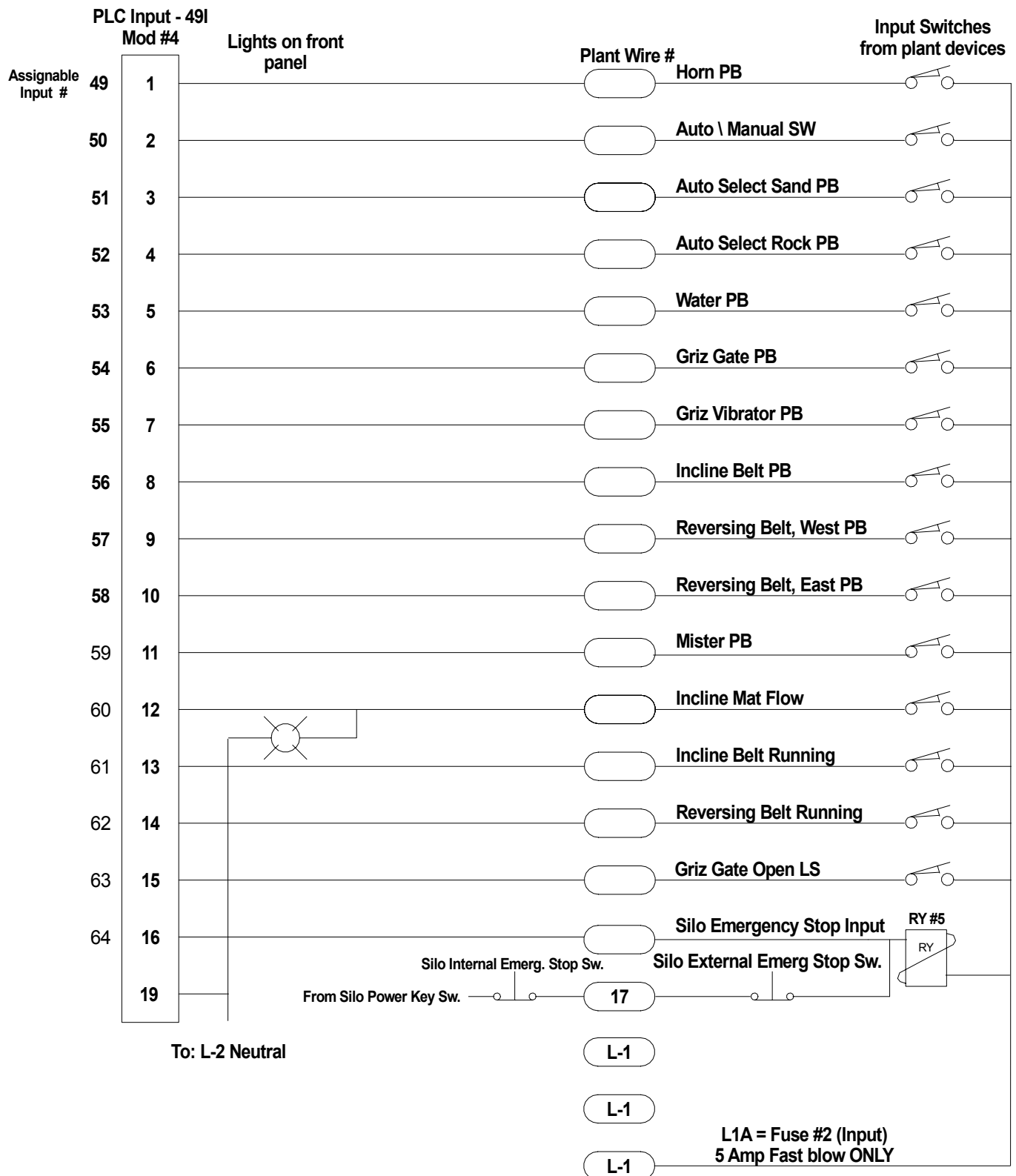


L1A = Fuse #2 (Input)
5 Amp Fast blow ONLY

This 120 VAC can be used for powering Bindicators motors and other input related items.
Max. power = 5 Amps total ALL connected loads.

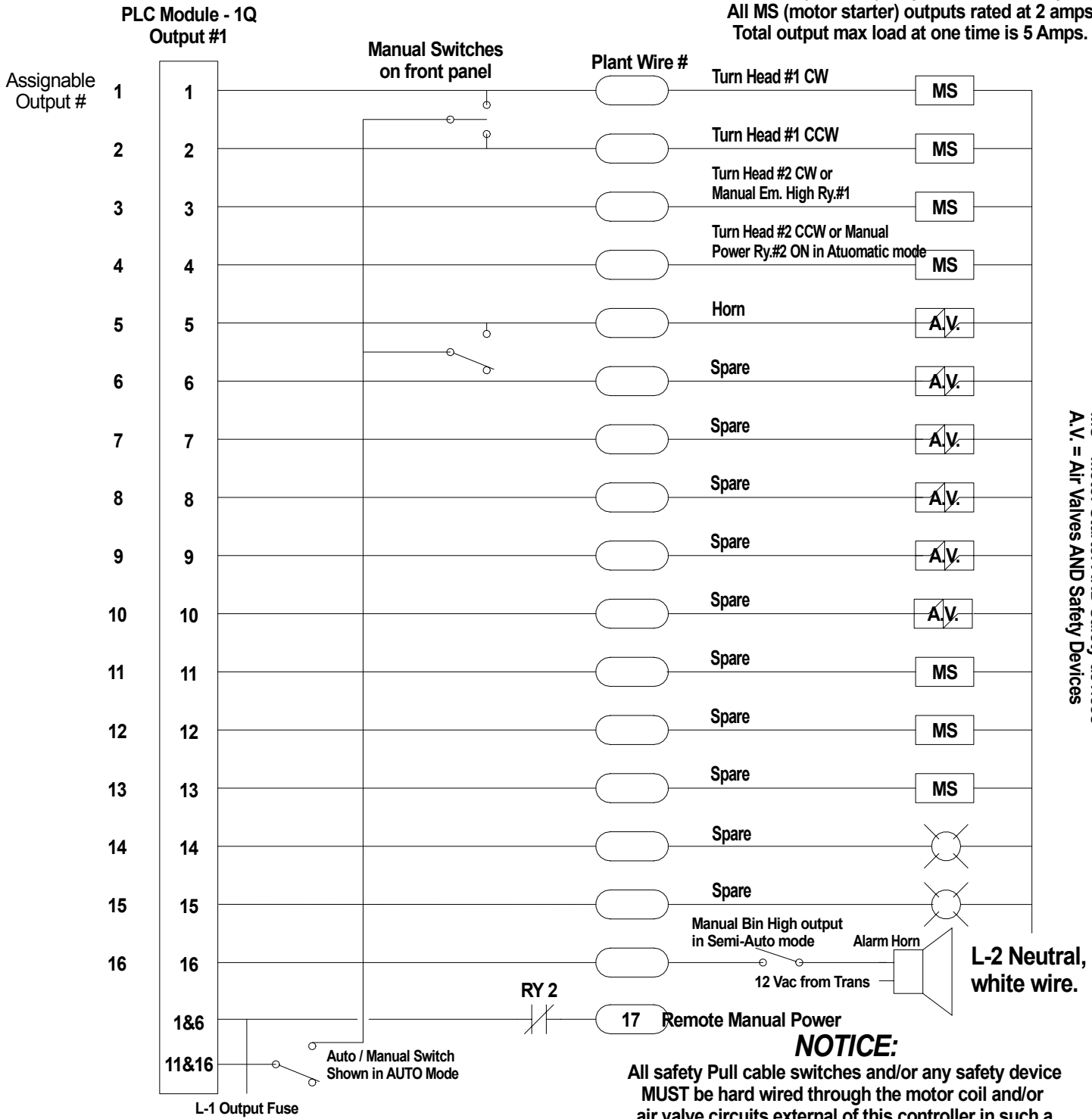


This 120 VAC can be used for powering B indicators
motors and other input related items.
Max. power = 5 Amps total ALL connected loads.



This 120 VAC can be used for powering Bindicators motors and other input related items.
Max. power = 5 Amps total ALL connected loads.

All AV (air valve) outputs rated at 2 amp.
 All MS (motor starter) outputs rated at 2 amps
 Total output max load at one time is 5 Amps.



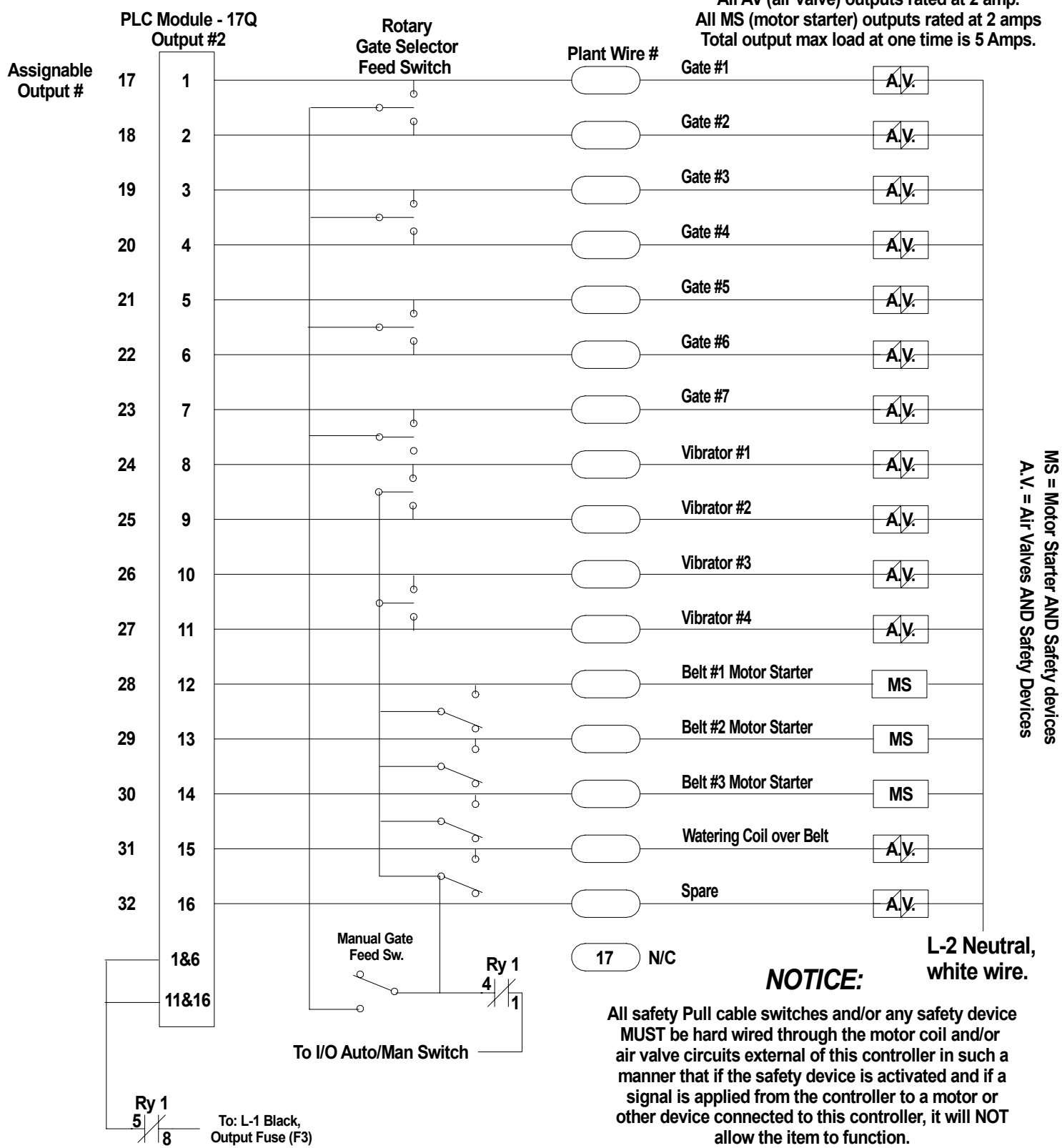
MS = Motor Starter AND Safety devices
 A.V. = Air Valves AND Safety Devices

NOTICE:

All safety Pull cable switches and/or any safety device MUST be hard wired through the motor coil and/or air valve circuits external of this controller in such a manner that if the safety device is activated and if a signal is applied from the controller to a motor or other device connected to this controller, it will NOT allow the item to function.

If the turnhead / Shuttle Belt is reversible, travel limit switches MUST be installed at each end of the turnhead / Shuttle travel and hard wired through the motor coil circuits external of this controller in such a manner that if a signal is applied from the controller to the turnhead / Shuttle Belt it will NOT allow the turnhead / Shuttle Belt to function beyond the turnhead / Shuttle Belt travel limits in either direction.

All AV (air valve) outputs rated at 2 amp.
 All MS (motor starter) outputs rated at 2 amps
 Total output max load at one time is 5 Amps.



MS = Motor Starter AND Safety devices
 A.V. = Air Valves AND Safety Devices

17 N/C

L-2 Neutral, white wire.

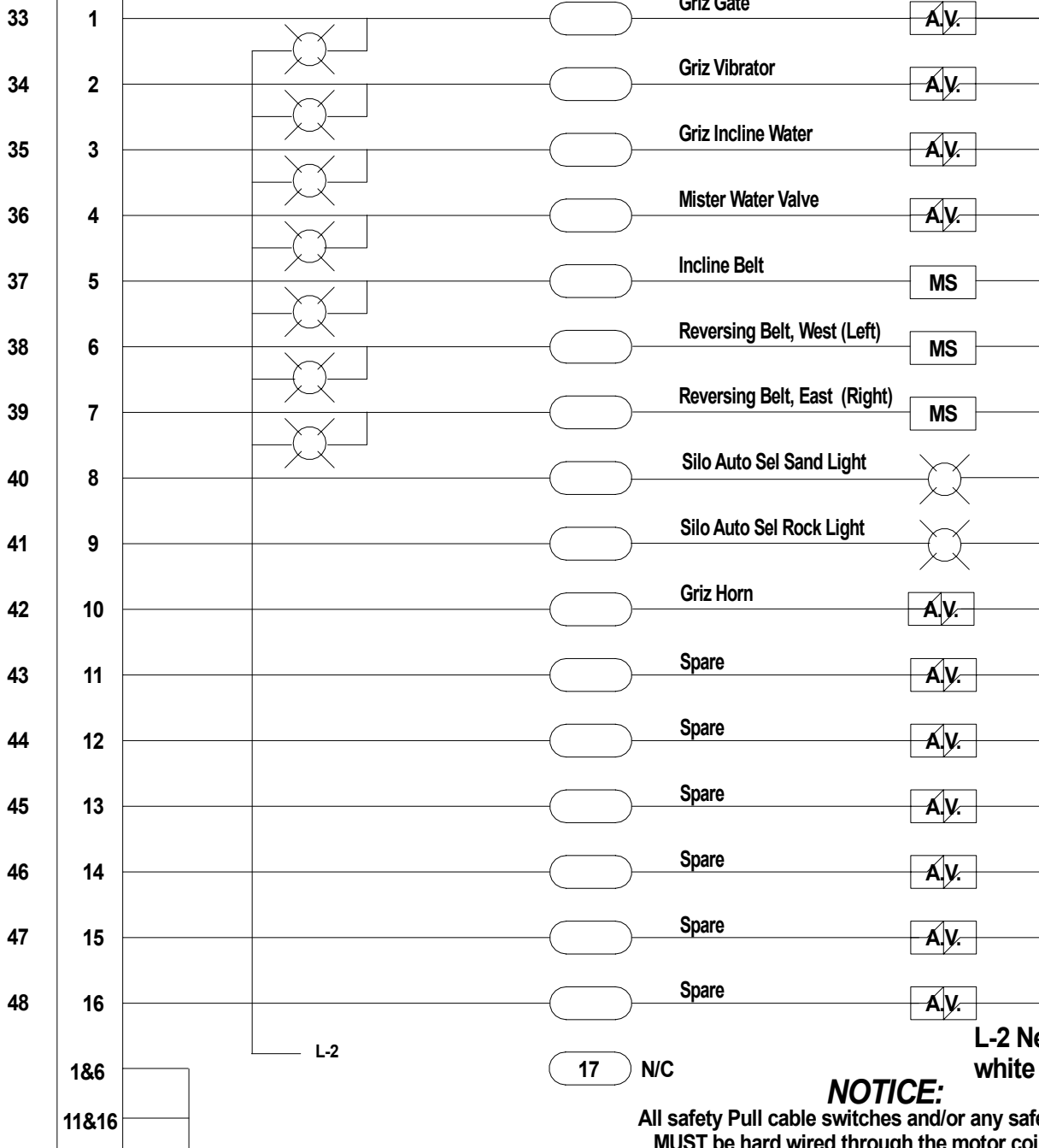
NOTICE:

All safety Pull cable switches and/or any safety device MUST be hard wired through the motor coil and/or air valve circuits external of this controller in such a manner that if the safety device is activated and if a signal is applied from the controller to a motor or other device connected to this controller, it will NOT allow the item to function.

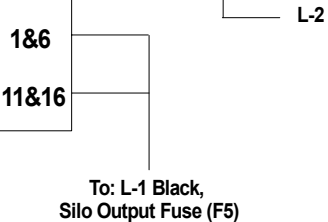
If the turnhead / Shuttle Belt is reversible, travel limit switches MUST be installed at each end of the turnhead / Shuttle travel and hard wired through the motor coil circuits external of this controller in such a manner that if a signal is applied from the controller to the turnhead / Shuttle Belt it will NOT allow the turnhead / Shuttle Belt to function beyond the turnhead / Shuttle Belt travel limits in either direction.

PLC Module - 33Q
Output #3

Assignable
Output #



MS = Motor Starter AND Safety devices
A.V. = Air Valves AND Safety Devices



L-2 Neutral, white wire.

NOTICE:

All safety Pull cable switches and/or any safety device MUST be hard wired through the motor coil and/or air valve circuits external of this controller in such a manner that if the safety device is activated and if a signal is applied from the controller to a motor or other device connected to this controller, it will NOT allow the item to function.

If the turnhead / Shuttle Belt is reversible, travel limit switches MUST be installed at each end of the turnhead / Shuttle travel and hard wired through the motor coil circuits external of this controller in such a manner that if a signal is applied from the controller to the turnhead / Shuttle Belt it will NOT allow the turnhead / Shuttle Belt to function beyond the turnhead / Shuttle Belt travel limits in either direction.

J.H.M.C. Robotics, Inc.

HANDLER REGAL plant wiring Diagrams. Date:08/16/2005